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Abstract

This paper considers the problem of inference for nested least squares averaging estimators. We study the asymptotic behavior of the Mallows model averaging estimator (MMA; Hansen, 2007) and the jackknife model averaging estimator (JMA; Hansen and Racine, 2012) under the standard asymptotics with fixed parameters setup. We find that both MMA and JMA estimators asymptotically assign zero weight to the under-fitted models, and MMA and JMA weights of just-fitted and over-fitted models are asymptotically random. Building on the asymptotic behavior of model weights, we derive the asymptotic distributions of MMA and JMA estimators and propose a simulation-based confidence interval for the least squares averaging estimator. Monte Carlo simulations show that the coverage probabilities of proposed confidence intervals achieve the nominal level.

Keywords: Confidence intervals, Inference post-model-averaging, Jackknife model averaging, Mallows model averaging.

JEL Classification: C51, C52

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1 Introduction

In the past two decades, model averaging from the frequentist perspective has received much attention in both statistics and econometrics. Model averaging considers the uncertainty across different models as well as the model bias from each candidate model via effectively averaging over all potential models. Different methods of weight selection have been proposed based on distinct criteria; see Claeskens and Hjort (2008) and Moral-Benito (2015) for a literature review. Despite the growing literature on frequentist model averaging, little work has been done on examining the asymptotic behavior of the model averaging estimator.

Recently, Hansen (2014) and Liu (2015) study the limiting distributions of the least squares averaging estimators in a local asymptotic framework where the regression coefficients are in a local $n^{-1/2}$ neighborhood of zero. The merit of the local asymptotic framework is that both squared model biases and estimator variances have the same order $O(n^{-1})$. Thus, the asymptotic mean squared error remains finite and provides a good approximation to finite sample mean squared error in this context. However, there has been a discussion about the realism of the local asymptotic framework; see Hjort and Claeskens (2003b) and Raftery and Zheng (2003). Furthermore, the local asymptotic framework induces the local parameters in the asymptotics, which generally cannot be estimated consistently. In this paper, instead of assuming drifting sequences of parameters, we consider the standard asymptotics with fixed parameters setup and investigate the asymptotic distribution of the nested least squares averaging estimator.

For frequentist model averaging, estimated weights are asymptotically random. Therefore, it is important to understand the behavior of the selected weights as the sample size increases. Under the fixed parameter framework, we study the asymptotic behavior of model weights selected by the MMA and JMA estimators. We find that both MMA and JMA estimators asymptotically assign zero weight to the under-fitted model, that is, a model with omitted variables. This novel result implies that both MMA and JMA estimators only average over just-fitted and over-fitted models but not under-fitted models. Unlike the weight of the under-fitted model, MMA and JMA weights of just-fitted and over-fitted models have nonstandard limiting distributions, but they could be characterized by a normal random vector. Building on the asymptotic behavior of model weights, we show that the asymptotic distributions of MMA and JMA estimators are both nonstandard. The main difference between our results and those of Hansen (2014) and Liu (2015) is that our limiting distribution is a nonlinear function of the normal random vector with mean zero, while their limiting
distributions depend on a nonlinear function of the normal random vector plus the local parameters.

The limiting distributions of the least squares averaging estimators are nonstandard and not pivotal and thus cannot be used for inference directly. To address this issue, we propose a simulation-based method to construct the confidence intervals. The idea of the simulation-based confidence interval is to simulate the limiting distributions of averaging estimators and use this simulated distribution to conduct inference. Unlike the naive method, which ignores the model selection step and takes the selected model as the true model to construct the confidence intervals, the proposed method takes the model averaging step into account and has asymptotically the correct coverage probability.

As an alternative approach to the simulation-based confidence interval, we consider imposing a larger penalty term in the weight selection criterion such that the resulting weights of over-fitted models could converge to zeros. We show that this modified averaging estimator is asymptotically normal with the same covariance matrix as the least squares estimator for the just-fitted model. Therefore, we can use the critical value of the standard normal distribution to construct the traditional confidence interval. Monte Carlo simulations show that the coverage probabilities of these two proposed methods achieve the nominal level, while the naive confidence intervals that ignore the model selection step lead to distorted inference.

We now discuss the related literature. There are two main model averaging approaches, Bayesian model averaging and frequentist model averaging. Bayesian model averaging has a long history, and has been widely used in statistical and economic analysis; see Hoeting et al. (1999) for a literature review. In contrast to Bayesian model averaging, there is a growing body of literature on frequentist model averaging, including information criterion weighting (Buckland et al., 1997; Hjort and Claeskens, 2003a; Zhang and Liang, 2011; Zhang et al., 2012), adaptive regression by mixing models (Yang, 2000, 2001; Yuan and Yang, 2005), Mallows’ $C_p$-type averaging (Hansen, 2007; Wan et al., 2010; Liu and Okui, 2013; Zhang et al., 2014), optimal mean squared error averaging (Liang et al., 2011), jackknife model averaging (Hansen and Racine, 2012; Zhang et al., 2013; Lu and Su, 2015), and plug-in averaging (Liu, 2015). There are also many alternative approaches to model averaging, for example, bagging (Breiman, 1996; Inoue and Kilian, 2008), LASSO (Tibshirani, 1996), adaptive LASSO (Zou, 2006), and the model confidence set (Hansen et al., 2011), among others.
There is a large literature on inference after model selection, including Pötscher (1991), Kabaila (1995, 1998), Pötscher and Leeb (2009), and Leeb and Pötscher (2003, 2005, 2006, 2008, 2012). These papers point out that the coverage probabilities of naive confidence intervals are lower than the nominal values. They also claim that no uniformly consistent estimator exists for the conditional and unconditional distributions of post-model-selection estimators. The existing literature on inference after model averaging is comparatively small. Hjort and Claeskens (2003a) and Claeskens and Hjort (2008) show that the traditional confidence interval based on normal approximations leads to distorted inference. Pötscher (2006) argues that the finite-sample distribution of the averaging estimator cannot be uniformly consistently estimated. Hansen (2014) and Liu (2015) investigate the asymptotic distributions of the least squares averaging estimators in a local asymptotic framework. Claeskens and Hjort (2008), Lu (2015), and DiTraglia (2016) consider a simulation-based method to construct the confidence intervals of the averaging estimator in a local asymptotic framework. To our knowledge, the asymptotic behavior of the least squares averaging estimator has not been explored before under the standard asymptotics with fixed parameters setup.

The outline of the paper is as follows. Section 2 presents the model and the averaging estimator. Section 3 presents the MMA and JMA estimators. Section 4 presents the asymptotic framework and derives the limiting distributions of the MMA and JMA estimators. Section 5 proposes a simulation-based confidence interval and a modified least squares averaging estimator with asymptotic normality. Section 6 examines the finite sample properties of proposed methods, and Section 7 concludes the paper. Proofs and tables are included in the Appendix.

2 Model and Estimation

We consider a linear regression model:

\[ y_i = x_{1i}' \beta_1 + x_{2i}' \beta_2 + \epsilon_i, \]
\[ E(\epsilon_i | x_i) = 0, \]
\[ E(\epsilon_i^2 | x_i) = \sigma^2(x_i), \]

where \( y_i \) is a scalar dependent variable, \( x_i = (x_{1i}', x_{2i}')', x_{1i}(k_1 \times 1) \) and \( x_{2i}(k_2 \times 1) \) are vectors of regressors, \( \beta_1 \) and \( \beta_2 \) are unknown parameter vectors, and \( \epsilon_i \) is an unobservable regression error. The error term is allowed to be homoskedastic or heteroskedastic, and there is no further assumption on the distribution of the error term. Here, \( x_{1i} \) contain
the core regressors that must be included in the model based on theoretical grounds, while \( \mathbf{x}_{2i} \) contain the auxiliary regressors that may or may not be included in the model. The auxiliary regressors could be any nonlinear transformations of the original variables and the interaction terms between the regressors. Note that \( \mathbf{x}_{1i} \) may only include a constant term or even an empty matrix. The model (2.1) is widely used in the model averaging literature, for example, Magnus et al. (2010), and Liang et al. (2011), and Liu (2015).

Let \( \mathbf{y} = (y_1, \ldots, y_n)' \), \( \mathbf{X}_1 = (\mathbf{x}_{11}, \ldots, \mathbf{x}_{1n})' \), \( \mathbf{X}_2 = (\mathbf{x}_{21}, \ldots, \mathbf{x}_{2n})' \), and \( \mathbf{e} = (\epsilon_1, \ldots, \epsilon_n)' \). In matrix notation, we write the model (2.1) as

\[
\mathbf{y} = \mathbf{X}_1 \mathbf{\beta}_1 + \mathbf{X}_2 \mathbf{\beta}_2 + \mathbf{e} = \mathbf{X} \mathbf{\beta} + \mathbf{e},
\]

where \( \mathbf{X} = (\mathbf{X}_1, \mathbf{X}_2) \) and \( \mathbf{\beta} = (\mathbf{\beta}_1', \mathbf{\beta}_2')' \). Let \( K = k_1 + k_2 \) be the number of regressors in the model (2.4). We assume that \( \mathbf{X} \) has full column rank \( K \).

Suppose that we have a set of \( M \) candidate models. We follow Hansen (2007, 2008, 2014) and consider a sequence of nested candidate models. In most applications, we have \( M = k_2 + 1 \) candidate models. The \( m \)th submodel includes all regressors in \( \mathbf{X}_1 \) and the first \( m - 1 \) regressors in \( \mathbf{X}_2 \), but excludes the remaining regressors. We use \( \mathbf{X}_{2m} \) to denote the auxiliary regressors included in the \( m \)th submodel. Note that the \( m \)th model has \( k_1 + k_{2m} = K_m \) regressors. In empirical applications, practitioners can order regressors by some manner or prior and then combine nested models. Similar to Hansen (2014), for all the following theoretical results, we do not impose any assumption on the ordering of regressors, i.e., the ordering is not required to be “correct” in any sense. A candidate model is called under-fitted if the model has omitted variables with nonzero slope coefficients. A candidate model is called just-fitted if the model has no omitted variable and no irrelevant variable, while a candidate model is called over-fitted if the model has no omitted variable but has irrelevant variables.\(^1\) Without loss of generality, we assume that the first \( M_0 \) candidate models are under-fitted. Obviously, we have \( M > M_0 > 0 \).

Let \( \mathbf{I} \) denote an identity matrix and \( \mathbf{0} \) a zero matrix. Let \( \Pi_m \) be a selection matrix so that \( \Pi_m = (\mathbf{I}_{K_m}, \mathbf{0}_{K_m \times (K - K_m)}) \) or a column permutation thereof and thus \( \mathbf{X}_m = (\mathbf{X}_1, \mathbf{X}_{2m}) = \mathbf{X} \Pi_m' \). The least squares estimator of \( \mathbf{\beta} \) in the \( m \)th candidate model is

\[
\hat{\mathbf{\beta}}_m = \Pi_m'(\mathbf{X}_m' \mathbf{X}_m)^{-1} \mathbf{X}_m' \mathbf{y}.
\]

\(^1\)In the case where there is no true model among all candidate models, i.e., all candidate models have omitted variables or irrelevant variables, the just-fitted model is the model that has no omitted variable and the smallest number of irrelevant variables and the over-fitted model is the model that has no omitted variable but more irrelevant variables than the just-fitted model.
We now define the least squares averaging estimator of $\beta$. Let $w_m$ be the weight corresponding to the $m$th candidate model and $w = (w_1, \ldots, w_M)'$ be a weight vector belonging to the weight set $W = \{w \in [0,1]^M : \sum_{m=1}^M w_m = 1\}$. That is, the weight vector lies in the unit simplex in $\mathbb{R}^M$. The least squares averaging estimator of $\beta$ is

$$\hat{\beta}(w) = \sum_{m=1}^M w_m \beta_m.$$  

(2.5)

### 3 Least Squares Averaging Estimator

In this section, we consider two commonly used methods of least squares averaging estimators, the Mallows model averaging (MMA) estimator and the jackknife model averaging (JMA) estimator.

Hansen (2007) introduces the Mallows model averaging estimator for the homoskedastic linear regression model. Let $P_m = X_m(X_m'X_m)^{-1}X_m'$ and $P(w) = \sum_{m=1}^M w_m P_m$ be the projection matrices. Let $\| \cdot \|^2$ stand for the Euclidean norm. The MMA estimator selects the model weights by minimizing a Mallows criterion

$$C(w) = \| (I_n - P(w))y \|^2 + 2\sigma^2 w'K,$$

(3.1)

where $\sigma^2 = E(e_i^2)$ and $K = (K_1, \ldots, K_M)'$. In practice, $\sigma^2$ can be estimated by $\hat{\sigma}^2 = (n - K)^{-1}y - X\hat{\beta}_M \|^2$. Denote $\hat{w}_{\text{MMA}} = \arg \min_{w \in W} C(w)$ as the MMA weights. Note that the criterion function $C(w)$ is a quadratic function of the weight vector. Therefore, the MMA weights can be found numerically via quadratic programming. The MMA estimator of $\beta$ is

$$\hat{\beta}(\hat{w}_{\text{MMA}}) = \sum_{m=1}^M \hat{w}_{\text{MMA},m} \hat{\beta}_m.$$  

(3.2)

Hansen (2007) demonstrates the asymptotic optimality of the MMA estimator for nested and homoskedastic linear regression models, i.e., the MMA estimator asymptotically achieves the lowest possible mean squared error among all candidates. However, the optimality of MMA fails under heteroskedasticity (Hansen, 2007).

Hansen and Racine (2012) introduce the jackknife model averaging estimator and demonstrate its optimality in the linear regression model with heteroskedastic errors. Let $h_{ii}^m$ be the $i$th diagonal element of $P_m$. Define $D_m$ as a diagonal matrix with $(1 - h_{ii}^m)^{-1}$ being its $i$th diagonal element. Let $\tilde{P}_m = D_m(P_m - I_n) + I_n$ and $\tilde{P}(w) = \sum_{m=1}^M w_m \tilde{P}_m$. The JMA estimator selects the weights by minimizing a cross-validation (or jackknife) criterion

$$J(w) = \|(I_n - \tilde{P}(w))y\|^2.$$  

(3.3)
Similar to the MMA estimator, the JMA weights can also be found numerically via quadratic programming. Denote \( \hat{w}_{\text{JMA}} = \arg \min_{w \in Y} J(w) \) as the JMA weights. Thus, the JMA estimator of \( \beta \) is

\[
\hat{\beta}(\hat{w}_{\text{JMA}}) = \sum_{m=1}^{M} \hat{w}_{\text{JMA},m} \hat{\beta}_m.
\] (3.4)

Hansen (2007) and Hansen and Racine (2012) demonstrate the asymptotic optimality of the MMA and JMA estimators in homoskedastic and heteroskedastic settings, respectively. However, there is no asymptotic distribution available in either paper. Hansen (2014) and Liu (2015) derives the asymptotic distributions of the MMA and JMA estimators in a local asymptotic framework where the regression coefficients are in a local \( n^{-1/2} \) neighborhood of zero. Unlike Hansen (2014) and Liu (2015), which assume a drifting sequence of the parameter, we investigate the asymptotic distributions of the MMA and JMA estimators under the standard asymptotics with fixed parameters setup in the next section.

4 Asymptotic Theory

In this section, we study the limiting distributions of the least squares averaging estimators. We now state the regularity conditions required for asymptotic results, where all limiting processes here and throughout the text are with respect to \( n \to \infty \).

Condition (C.1). \( Q_n = n^{-1}X'X \xrightarrow{p} Q \), where \( Q = E(x_ix'_i) \) is a positive definite matrix.

Condition (C.2). \( Z_n = n^{-1/2}X'e \xrightarrow{d} Z \sim N(0, \Omega) \), where \( \Omega = E(x_ix'_i\epsilon^2_i) \) is a positive definite matrix.

Condition (C.3). \( \bar{h}_n \equiv \max_{1 \leq m \leq M} \max_{1 \leq i \leq n} h_{ii}^m = o_p(n^{-1/2}) \).

Condition (C.4). \( \Omega_n = n^{-1} \sum_{i=1}^{n} x_ix'_i\epsilon^2_i \xrightarrow{p} \Omega. \)

Conditions (C.1), (C.2) and (C.4) are high-level conditions that permits the application of cross-section, panel, and time-series data. Conditions (C.1) and (C.2) are similar to Assumption 2 of Liu (2015). Conditions (C.1) and (C.2) hold under appropriate primitive

\(^2\)It is possible that the MMA and JMA estimators are not asymptotically optimal in our framework. This is because the condition (15) of Hansen (2007) and the condition (A.7) of Hansen and Racine (2012) do not hold under the standard asymptotics with a finite number of regressions. These sufficient conditions require that there be no submodel \( m \) for which the bias is zero, which does not hold in our framework since the just-fitted and over-fitted models have no bias.
assumptions. For example, if \( y_i \) is a stationary and ergodic martingale difference sequence with finite fourth moments, then these conditions follow from the weak law of large numbers and the central limit theorem for martingale difference sequences. Condition (C.4) is similar to the condition in Theorem 3 of Liu (2015). The sufficient condition for Condition (C.4) is that \( e_i \) is i.i.d. or a martingale difference sequence with finite fourth moments. Condition (C.3) is quite mild. Note that Li (1987) and Andrews (1991) assumed that \( h_{ii}^m \leq cK_mn^{-1} \) for some constant \( c < \infty \), which is more restrictive than Condition (C.3) under our model (2.1). Condition (C.3) is similar to Condition A.9 in Hansen and Racine (2012) and Assumption 2.4 in Liu and Okui (2013).

4.1 Asymptotic Distribution of the MMA Estimator

We first study the behavior of the MMA weights as \( n \to \infty \). The weights selected by the MMA estimator are random, and this must be taken into account in the asymptotic distribution of the MMA estimator. The following theorem describes the asymptotic behavior of the MMA weights of under-fitted models.

**Theorem 1.** Suppose that Conditions (C.1)-(C.2) hold. Then for any \( m \in \{1, \ldots, M_0\} \),

\[
\hat{w}_{\text{MMA},m} = O_p(n^{-1}).
\] (4.1)

Theorem 1 shows that the MMA weights of under-fitted models are \( O_p(n^{-1}) \). This result implies that the MMA estimator asymptotically assigns zero weight to the model that has omitted variables with nonzero parameters \( \beta_2 \). We next study the MMA weights of just-fitted and over-fitted models, i.e., \( m \in \{M_0 + 1, \ldots, M\} \), and the asymptotic distribution of the MMA estimator.

Let \( S = M - M_0 \) be the number of just-fitted and over-fitted models, which is not smaller than 1. Excluding the under-fitted models, we define a new weight vector \( \lambda = (\lambda_1, \ldots, \lambda_S)' \) that belongs to a weight set

\[
\mathcal{L} = \left\{ \lambda \in [0, 1]^S : \sum_{s=1}^S \lambda_s = 1 \right\}.
\] (4.2)

Note that the weight vector \( \lambda \) lies in the unit simplex in \( \mathbb{R}^S \). For \( s = 1, \ldots, S \), let \( \Omega_s = \Pi_{M_0+s}^t \Omega \Pi_{M_0+s}^t \), \( Q_s = \Pi_{M_0+s}^t Q \Pi_{M_0+s}^t \), and \( V_s = \Pi_{M_0+s}^t Q_s^{-1} \Pi_{M_0+s}^t \) be the covariance matrices associated with the new weight vector, where \( \Omega \) and \( Q \) are defined in Conditions (C.1)-(C.2).
Theorem 2. Suppose that Conditions (C.1)-(C.2) hold. Then we have

\[
\sqrt{n}(\hat{\beta}(\hat{w}_{\text{MMA}}) - \beta) = \sum_{m=1}^{M_0} \hat{w}_{\text{MMA},m} \sqrt{n}(\hat{\beta}_m - \beta) + \sum_{m=M_0+1}^{M} \hat{w}_{\text{MMA},m} \sqrt{n}(\hat{\beta}_m - \beta)
\]

\[
= O_p(n^{-1/2}) + \sum_{m=M_0+1}^{M} \hat{w}_{\text{MMA},m} \Pi_m' (\Pi_m Q_m \Pi_m')^{-1} \Pi_m Z_n
\]

\[
\rightarrow \sum_{s=1}^{S} \tilde{\lambda}_{\text{MMA},s} V_s Z
\] (4.3)

in distribution, where \( \tilde{\lambda}_{\text{MMA}} = (\tilde{\lambda}_{\text{MMA},1}, \ldots, \tilde{\lambda}_{\text{MMA},S})' = \text{arg min}_{\lambda \in \mathcal{L}} \lambda' \Gamma \lambda \) and \( \Gamma \) is an \( S \times S \) matrix with the \((s,j)\)th element

\[
\Gamma_{sj} = 2\sigma^2 K_{M_0+s} - ZV_{\text{max}(s,j)}Z.
\] (4.4)

Theorem 2 shows that the MMA weights of just-fitted and over-fitted models have non-standard asymptotic distributions since \( \Gamma \) is a nonlinear function of the normal random vector \( Z \). Furthermore, the MMA estimator has a nonstandard limiting distribution, which can be expressed in terms of the normal random vector \( Z \). The representation (4.3) also implies that in the large sample sense, the just-fitted and over-fitted models can receive positive weight, while the under-fitted models receive zero weight.\(^3\)

Hansen (2014) and Liu (2015) also derive the asymptotic distribution of the MMA estimator. Both papers consider the local-to-zero asymptotic framework, that is, \( \beta_2 = \beta_{2n} = \delta / \sqrt{n} \) and \( \delta \) is an unknown local parameter. Note that the local parameters generally cannot be estimated consistently. The main difference between Theorem 2 and results in Hansen (2014) and Liu (2015) is that our limiting distribution does not depend on the local parameters.

### 4.2 Asymptotic Distribution of the JMA Estimator

We now study the asymptotic behavior of the JMA weights and the asymptotic distribution of the JMA estimator.

Theorem 3. Suppose that Conditions (C.1)-(C.3) hold. Then for any \( m \in \{1, \ldots, M_0\} \),

\[
\hat{w}_{\text{JMA},m} = o_p(n^{-1/2}).
\] (4.5)

---

\(^3\)The least squares estimator with more variables tends to have a larger variance in the nested framework. However, when the error term is heteroskedastic, it is possible that adding an irrelevant variable could decrease the estimation variance; see the example on pages 209–210 of Hansen (2017).
Similar to Theorem 1, Theorem 3 shows that the JMA estimator asymptotically assigns zero weight to under-fitted models. The next theorem provides the asymptotic distribution of the JMA estimator.

**Theorem 4.** Suppose that Conditions (C.1)-(C.4) hold. Then we have

$$
\sqrt{n}(\hat{\beta}(\hat{w}_{JMA}) - \beta) = \sum_{m=1}^{M_0} \hat{w}_{JMA,m} \sqrt{n}(\hat{\beta}_m - \beta) + \sum_{m=M_0+1}^{M} \hat{w}_{JMA,m} \sqrt{n}(\hat{\beta}_m - \beta)
$$

$$
= o_p(1) + \sum_{m=M_0+1}^{M} \hat{w}_{JMA,m} \Pi_m' (\Pi_m Q_m \Pi_m')^{-1} \Pi_m Z_n
$$

$$
\to \sum_{s=1}^{S} \tilde{\lambda}_{JMA,s} V_s Z
$$

(4.6)

in distribution, where $\tilde{\lambda}_{JMA} = (\tilde{\lambda}_{JMA,1}, \ldots, \tilde{\lambda}_{JMA,S})' = \arg \min_{\lambda \in \mathcal{L}} \lambda' \Sigma \lambda$ and $\Sigma$ is an $S \times S$ matrix with the $(s,j)$th element

$$
\Sigma_{sj} = tr(Q_s^{-1} \Omega_s) + tr(Q_j^{-1} \Omega_j) - Z' \max_{s,j} Z.
$$

(4.7)

Similar to Theorem 2, Theorem 4 shows that the JMA estimator has a nonstandard asymptotic distribution. The main difference between Theorem 2 and 4 is the limiting behavior of the weight vector, i.e., $\tilde{\lambda}_{MMA,s}$ and $\tilde{\lambda}_{JMA,s}$. The first term of $\Gamma_{sj}$ in (4.4) is the limit of the penalty term of the Mallows criterion, and the second term of $\Gamma_{sj}$ is the limit of the in-sample squared error $\|y - X\hat{\beta}_{M_0+\max\{s,j\}}\|^2$ subtracting the term $\|e\|^2$, which is unrelated to $\lambda$. Since the second term of $\Gamma_{sj}$ is the same as the last term of $\Sigma_{sj}$ in (4.7), the asymptotic distributions of MMA and JMA estimators differ only in the limit of the penalty terms. Note that for the homoskedastic situation, $\Omega = \sigma^2 Q$, by which we have $tr(Q_s^{-1} \Omega_s) = \sigma^2 K_{M_0+s}$, and thus $\tilde{\lambda}_{MMA,s} = \tilde{\lambda}_{JMA,s}$. This result means that the limiting distributions of the MMA and JMA estimators are the same for the homoskedastic situation, which is reasonable and expected.

## 5 Inference for Least Squares Averaging Estimators

In this section, we investigate the problem of inference for least squares averaging estimators. To address this problem, we propose a simulation-based method to construct the confidence intervals. We also propose a modified JMA estimator and demonstrate its asymptotic normality.
5.1 Simulation-Based Confidence Intervals

As shown in the previous section, the least squares averaging estimator with data-dependent weights has a nonstandard asymptotic distribution. Since the asymptotic distributions derived in Theorems 2 and 4 are not pivotal, they cannot be directly used for inference. To address this issue, we follow Claeskens and Hjort (2008), Lu (2015), and DiTraglia (2016), and consider a simulation-based method to construct the confidence intervals.

In Theorems 2 and 4, we show that the asymptotic distribution of the least squares averaging estimator is a nonlinear function of unknown parameters \( \sigma^2, \Omega, \) and \( Q, \) and the normal random vector \( Z. \) Suppose that \( \sigma^2, \Omega, \) and \( Q \) were all known. Then, by simulating from \( Z \) defined in Condition (C.2), we could approximate the limiting distributions defined in Theorems 2 and 4 to arbitrary precision. This is the main idea of the simulation-based confidence intervals. In practice, we replace the unknown parameters with the consistent estimators. We then simulate the limiting distributions of least squares averaging estimators and use this simulated distribution to conduct inference.

We now describe the simulation-based confidence intervals in details. Let \( \hat{e}_i \) be the least squares residual from the full model, i.e., \( \hat{e}_i = y_i - x_i \hat{\beta}_M, \) where \( \hat{\beta}_M = (X'X)^{-1}X'y. \) Then, \( \hat{\sigma}^2 = \frac{1}{n-K} \sum_{i=1}^n \hat{e}_i^2 \) is the consistent estimator of \( \sigma^2. \) Also, \( \hat{Q} = \frac{1}{n} \sum_{i=1}^n x_i x_i' = Q_n \) and \( \hat{\Omega} = \frac{1}{n} \sum_{i=1}^n x_i x_i' \hat{e}_i^2 \) are consistent estimators of \( Q \) and \( \Omega, \) respectively. We propose the following algorithm to obtain the simulation-based confidence interval for \( \beta_j. \)

- **Step 1:** Estimate the full model and obtain the consistent estimators \( \hat{\sigma}^2, \hat{Q}, \) and \( \hat{\Omega}. \)
- **Step 2:** Generate a sufficiently large number of \( K \times 1 \) normal random vector \( \mathbf{Z}^{(r)} \sim \mathcal{N}(0, \hat{\Omega}) \) for \( r = 1, \ldots, R. \) For each \( r, \) we compute the quantities of the asymptotic distributions derived in Theorem 2 or 4 based on the sample analogue \( \hat{\sigma}^2, \hat{Q}, \) and \( \hat{\Omega}. \) That is, we first calculate \( \hat{V}_s = \Pi'_{M_o+s} \hat{Q}_s^{-1} \Pi_{M_o+s} \) and \( \hat{Q}_s = \Pi_{M_o+s} \hat{\Omega} \Pi'_{M_o+s} \) for a given \( M_0. \) We then compute \( \sum_{s=1}^S \hat{\lambda}^{(r)}_{\lambda_{MMA},s}(M_0) \hat{V}_s \mathbf{Z}^{(r)} \) or \( \sum_{s=1}^S \hat{\lambda}^{(r)}_{\lambda_{JMA},s}(M_0) \hat{V}_s \mathbf{Z}^{(r)}, \) where \( \hat{\lambda}^{(r)}_{\lambda_{MMA},s}(M_0) = \arg \min_{\lambda \in \mathcal{L}} \lambda \hat{\Gamma}^{(r)}(M_0) \lambda, \) \( \hat{\lambda}^{(r)}_{\lambda_{JMA}} = \arg \min_{\lambda \in \mathcal{L}} \lambda \hat{\Sigma}^{(r)}(M_0) \lambda, \) and the \( (s,j) \)th element of \( \hat{\Gamma}^{(r)}(M_0) \) and \( \hat{\Sigma}^{(r)}(M_0) \) are

\[
\hat{\Gamma}^{(r)}_{sj}(M_0) = 2\hat{\sigma}^2 K_{M_o+s} - \mathbf{Z}^{(r)'} \hat{\Omega}_{\max(s,j)} \mathbf{Z}^{(r)}, \\
\hat{\Sigma}^{(r)}_{sj}(M_0) = \text{tr}(\hat{Q}_s \hat{\Omega}_s^{-1}) + \text{tr}(\hat{Q}_s^{-1} \hat{\Omega}_s) - \mathbf{Z}^{(r)'} \hat{\Omega}_{\max(s,j)} \mathbf{Z}^{(r)},
\]

for \( M_0 = 0, \ldots, M-1, \) respectively. Let \( \Lambda^{(r)}_{\lambda_{MMA},j}(\hat{w}_{JMA}) = \sum_{M_0=0}^{M-1} \hat{w}_{JMA,M_0+1}^{(r)} \Lambda^{(r)}_{\lambda_{MMA},j}(M_0) \) and \( \Lambda^{(r)}_{\lambda_{JMA},j}(\hat{w}_{JMA}) = \sum_{M_0=0}^{M-1} \hat{w}_{JMA,M_0+1}^{(r)} \Lambda^{(r)}_{\lambda_{JMA},j}(M_0), \) where \( \hat{w}_{JMA} \) are the modified JMA
weights defined in the next subsection, and $\Lambda_{\text{MMA},q}^{(r)}(M_0)$ and $\Lambda_{\text{JMA},q}^{(r)}(M_0)$ are the $j$th component of $\sum_{s=1}^{S} \tilde{\lambda}_{\text{MMA},s}(M_0) \tilde{V}_s Z^{(r)}$ and $\sum_{s=1}^{S} \tilde{\lambda}_{\text{JMA},s}(M_0) \tilde{V}_s Z^{(r)}$, respectively.\footnote{Note that the value of $M_0$ is unknown in practice. As suggested by a referee, we average over all models when we simulate the asymptotic distribution. Based on Theorem 5, one would expect the modified JMA weights of under-fitted and over-fitted models should be small in the finite sample.}

- Step 3: Let $\hat{q}_j(\alpha/2)$ and $\hat{q}_j(1 - \alpha/2)$ be the $(\alpha/2)$th and $(1 - \alpha/2)$th quantiles of $\Lambda_{\text{MMA},q}^{(r)}(\tilde{w}_{\text{JMA}})$ or $\Lambda_{\text{JMA},q}^{(r)}(\tilde{w}_{\text{JMA}})$ for $r = 1, \ldots, R$, respectively.

- Step 4: Let $\hat{\beta}_j(\tilde{w})$ be the $j$th component of $\hat{\beta}(\tilde{w})$, where $\tilde{w}$ is either $\tilde{w}_{\text{MMA}}$ or $\tilde{w}_{\text{JMA}}$.

The confidence interval of $\beta_j$ is constructed as

$$CI_n = \left[\hat{\beta}_j(\tilde{w}) - n^{-1/2} \hat{q}_j(1 - \alpha/2), \hat{\beta}_j(\tilde{w}) - n^{-1/2} \hat{q}_j(\alpha/2)\right]. \quad (5.1)$$

Given the consistent estimators $\hat{\sigma}^2$, $\hat{G}$, and $\hat{\Omega}$, the proposed confidence interval $CI_n$ yields valid inference for $\beta_j$.\footnote{The proposed simulation-based method can be easily extended to joint tests. Suppose that the parameter of interest is $\theta = g(\beta)$ for some function $g : \mathbb{R}^K \to \mathbb{R}^L$. Let $\hat{\theta} = g(\hat{\beta}(\tilde{w}_{\text{MMA}}))$ be the estimate of $\theta$. Applying the delta method to Theorem 2, we have $\sqrt{n}(\hat{\theta} - \theta) \to \sum_{s=1}^{S} \tilde{\lambda}_{\text{MMA},s} G' \tilde{V}_s Z$ in distribution, where $G = \frac{\partial g(\beta)}{\partial \beta}'$. Then we can conduct joint tests similarly to the proposed algorithm.} Thus, the confidence interval $CI_n$ has asymptotically the correct coverage probability as $R, n \to \infty$.\footnote{Note that our asymptotic results are pointwise but not uniform. Although developing the uniform inference results is important, such an investigation is beyond the scope of this paper, and thus it is left for future research.}

Note that both Lu (2015), and DiTraglia (2016) propose a two-step algorithm to construct the simulation-based confidence intervals since they need to construct a confidence region for the local parameters first. Our proposed algorithm is a one-step procedure since the limiting distributions derived in Theorems 2 and 4 do not depend on the local parameters.

### 5.2 Asymptotic Normality of Averaging Estimators

From the analysis in Section 4, we know that the MMA and JMA weights of under-fitted models converge to zeros, but the weights of the over-fitted models converge to random vectors $\tilde{\lambda}_{\text{MMA},1}, \ldots, \tilde{\lambda}_{\text{MMA},S}$ or $\tilde{\lambda}_{\text{JMA},1}, \ldots, \tilde{\lambda}_{\text{JMA},S}$. This is the main reason that the asymptotic distributions of the MMA and JMA estimators are nonstandard. To handle this problem, we propose a simulation-based confidence interval in the previous subsection. As an alternative approach, we can consider a larger penalty term in the weight selection criterion such that the resulting weights of over-fitted models could converge to zeros. Utilizing this idea, we could have asymptotic normality of the least squares averaging estimator.
We now present the details. We add a penalty term to the cross-validation criterion defined in (3.3) and obtain the following criterion

$$J(w) = \|(I_n - \hat{P}(w))y\|^2 + \phi_n w'K,$$

(5.2)

where $\phi_n$ is a tuning parameter to control the penalization level. Note that the modified JMA weights can also be found numerically via quadratic programming. Denote $\hat{w}_{JMA} = \arg\min_{w \in W} J(w)$ as the modified JMA weights. Thus, the modified JMA estimator of $\beta$ is defined as

$$\hat{\beta}(\hat{w}_{JMA}) = \sum_{m=1}^{M} \hat{w}_{JMA,m}\hat{\beta}_m.$$

(5.3)

The following theorem presents the asymptotic normality of the modified JMA estimator.

**Theorem 5.** Suppose that Conditions (C.1)-(C.3) hold and $\phi_n \to \infty$. Then for any $m \in \{M_0 + 2, \ldots, M\}$, we have

$$\hat{w}_{JMA,m} = O_p(\phi_n^{-1}).$$

(5.4)

Further if $\phi_n n^{-1/2} \to 0$, then we have

$$\sqrt{n}(\hat{\beta}(\hat{w}_{JMA}) - \beta) \to V_1Z \sim N(0, \Pi_{M_0+1}^{-1}Q_1^{-1}\Omega_1Q_1^{-1}\Pi_{M_0+1})$$

(5.5)

in distribution, where $V_1 = \Pi_{M_0+1}'Q_1^{-1}\Pi_{M_0+1}^{-1}$, $Q_1 = \Pi_{M_0+1}'Q_1\Pi_{M_0+1}$, and $\Omega_1 = \Pi_{M_0+1}'\Omega_1\Pi_{M_0+1}$.

The first part of Theorem 5 shows that the modified JMA weights of over-fitted models are $O_p(\phi_n^{-1})$, which implies that the modified JMA estimator asymptotically assigns zero weight to the over-fitted models as $\phi_n \to \infty$. For the tuning parameter $\phi_n$, we suggest to use $\log(n)$, which corresponds to the penalty term in Bayesian information criterion.

Recall that the $(M_0 + 1)$th model is the just-fitted model. The second result of Theorem 5 shows that the modified JMA estimator is asymptotically normal with the same covariance matrix as the least squares estimator for the just-fitted model. Since the asymptotic distribution is normal, we can use the standard normal critical value to construct the traditional confidence interval for $\beta_j$.

6 Simulation Study

In this section, we study the finite sample mean squared error and the coverage probability of the least square averaging estimator in comparison with other alternative approaches to model averaging.
6.1 Simulation Setup

We consider a linear regression model with a finite number of regressions

\[ y_i = \sum_{j=1}^{k} \beta_j x_{ji} + e_i, \]  

where \( x_{1i} = 1 \) and \((x_{2i}, ..., x_{ki})' \sim N(0, \Sigma_x)\). The diagonal elements of \( \Sigma_x \) are \( \rho \), and off-diagonal elements are \( \rho^2 \). We set \( \rho = 0.7 \). The error term is generated by \( e_i = \sigma_i \eta_i \). For the homoskedastic simulation, \( \eta_i \) is generated from a standard normal distribution, and \( \sigma_i = 2.5 \) for \( i = 1, ..., n \). For the heteroskedastic simulation, \( \eta_i \) is generated from a t-distribution with 4 degrees of freedom, and \( \sigma_i = (1 + 2|x_{4i}| + 4|x_{ki}|)/3 \) for \( i = 1, ..., n \). We let \((x_{1i}, x_{2i})\) be the core regressors and consider all other regressors auxiliary. We set \( k = 10 \) and consider a sequence of nested submodels. Thus, the number of models is \( M = 9 \).

Three cases of the regression coefficients are studied:

Case 1: \( \beta = (1, 1, c, c^2, c^3, c^4, 0, 0, 0)' \),

Case 2: \( \beta = (1, 1, c^4, c^3, c^2, c, 0, 0, 0)' \),

Case 3: \( \beta = (1, 1, c, c^2, 0, 0, c^3, c^4, 0, 0)' \).

We set \( c = 0.5 \). The numbers of under-fitted models are \( M_0 = 4, 4, \) and 6 for Case 1, 2, and 3, respectively. The regression coefficient is a decreasing sequence for Case 1 and 3, but not for Case 2. Only in Case 1, the ordering of regressors is correct. The ordering of regressors is not correct from the 2nd to 5th models in Case 2, and the ordering of regressors is not correct from the 4th to 6th models in Case 3.

6.2 Comparison with Other Approaches

In the Monte Carlo experiments, we consider the following estimators:

1. Least squares estimator for the just-fitted model (labeled JUST).
2. Least squares estimator for the largest model (labeled FULL).
3. Akaike information criterion model selection estimator (labeled AIC).
4. Bayesian information criterion model selection estimator (labeled BIC).
5. Adaptive LASSO estimator with bootstrap confidence intervals (labeled ALASSO)
6. MMA estimator with simulation-based confidence intervals (labeled MMA-S).
7. JMA estimator with simulation-based confidence intervals (labeled JMA-S).
8. MMA estimator with bootstrap confidence intervals (labeled MMA-B).
9. JMA estimator with bootstrap confidence intervals (labeled JMA-B).
10. Modified JMA estimator (labeled JMA-M).

We briefly discuss each estimator and how to construct the confidence intervals for each estimator. The JUST estimator is the least squares estimator for the \( (M_0 + 1) \)th model, while the FULL estimator is the least squares estimator for the \( M \)th model, i.e., the largest model. Let \( \hat{\beta}_j(m) \) denote the \( j \)th component of \( \hat{\beta}_m \) for \( m = M_0 + 1 \) or \( M \). For JUST and FULL, the confidence interval of \( \beta_j \) is constructed as

\[
CI_n = \left[ \hat{\beta}_j(m) - z_{1-\alpha/2}s(\hat{\beta}_j(m)), \hat{\beta}_j(m) + z_{1-\alpha/2}s(\hat{\beta}_j(m)) \right],
\]

where \( z_{1-\alpha/2} \) is \( 1 - \alpha/2 \) quantile of the standard normal distribution and \( s(\hat{\beta}_j(m)) \) is the standard error computed based on the \( m \)th model.

The AIC criterion for the \( m \)th model is \( AIC_m = n \log(\hat{\sigma}_m^2) + 2K_m \), where \( \hat{\sigma}_m^2 = \frac{1}{n} \sum_{i=1}^{n} \hat{e}_{mi}^2 \) and \( \hat{e}_{mi} \) is the least squares residual from the model \( m \). The BIC criterion for the \( m \)th model is \( BIC_m = n \log(\hat{\sigma}_m^2) + \log(n)K_m \). For both AIC and BIC, we construct the confidence intervals by a naive method. The naive approach ignores the model selection step and takes the selected model as the true model to construct the confidence intervals. For AIC and BIC, the naive confidence interval of \( \beta_j \) is constructed as

\[
CI_n = \left[ \hat{\beta}_j(\hat{m}) - z_{1-\alpha/2}s(\hat{\beta}_j(\hat{m})), \hat{\beta}_j(\hat{m}) + z_{1-\alpha/2}s(\hat{\beta}_j(\hat{m})) \right],
\]

where \( \hat{m} \) is the model selected by the AIC or BIC criterion, \( \hat{\beta}_j(\hat{m}) \) is the coefficient estimator under the selected model, and \( s(\hat{\beta}_j(\hat{m})) \) is the standard error computed by taking \( \hat{m} \) as the true model.

Zou (2006) proposed the adaptive LASSO estimator that simultaneously performs variable selection and estimation of the nonzero parameters in a linear regression model. The adaptive LASSO estimator minimizes the residual sum of squares subject to an \( \ell_1 \) penalty:

\[
\hat{\beta} = \arg\min_{\beta} \left( \sum_{i=1}^{n} (y_i - x_i^T \beta)^2 + \lambda_n \sum_{j=1}^{K} |\beta_j|^\gamma \right),
\]

where \( \hat{\beta} = (\hat{\beta}_1, ..., \hat{\beta}_K)' = (X'X)^{-1}X'y = \hat{\beta}_M \), \( \lambda_n \) is a turning parameter, and \( \gamma > 0.7\)

\footnote{In the simulations, we set \( \gamma = 2 \) and select the turning parameter \( \lambda_n \) by the generalized cross-validation method.}
We follow Chatterjee and Lahiri (2011) and use a residual bootstrap method to construct the confidence intervals for the adaptive LASSO estimator; see Chatterjee and Lahiri (2013) for the higher-order refinement of the bootstrap method, and Camponovo (2015) for a pairs bootstrap method for LASSO estimators. Let \( \bar{e}_i = y_i - x_i'\widehat{\beta} \) be the ALASSO residual, and \( \bar{e}_i^+ = \bar{e}_i - n^{-1} \sum_{i=1}^n \bar{e}_i \) be the centered value. The random samples \( \{e_1^*, \ldots, e_n^*\} \) are drawn from the centered residuals \( \{\bar{e}_1^+, \ldots, \bar{e}_n^+\} \) with replacement. The bootstrap samples are constructed by \( y_i^* = x_i'\widehat{\beta} + e_i^* \), and the bootstrap estimator is

\[
\widehat{\beta}^* = \arg\min_{\beta} \left( \sum_{i=1}^n (y_i^* - x_i'\beta)^2 + \lambda \sum_{j=1}^K \frac{|\beta_j|}{|\beta_j^*|} \right), \tag{6.5}
\]

where \( \widehat{\beta}^* = (\widehat{\beta}_1^*, \ldots, \widehat{\beta}_p^*)' = (X'X)^{-1}X'y^* \). Let \( \widehat{q}_j^*(\alpha) \) be the \( \alpha \)th quantile of the bootstrap distribution of \( |\sqrt{n}(\widehat{\beta}_j^* - \beta_j)| \), where \( \widehat{\beta}_j^* \) and \( \tilde{\beta}_j \) are \( j \)th component of \( \widehat{\beta}^* \) and \( \tilde{\beta} \), respectively. The bootstrap confidence interval of \( \beta_j \) is constructed as

\[
\text{CI}_n = \left[ \tilde{\beta}_j - n^{-1/2}\widehat{q}_j^*(\alpha), \tilde{\beta}_j + n^{-1/2}\widehat{q}_j^*(\alpha) \right]. \tag{6.6}
\]

The MMA and JMA estimators are defined in (3.2) and (3.4), respectively. The simulation-based confidence intervals for MMA-S and JMA-S are based on (5.1). We also consider a pairs bootstrap method to construct the confidence intervals for both MMA and JMA estimators.\(^8\) More precisely, let \( \{z_1, \ldots, z_n\} \) be the observation sample, where \( z_i = (y_i, x_i')' \). The random samples \( \{z_1^*, \ldots, z_n^*\} \) are drawn from \( \{z_1, \ldots, z_n\} \) with replacement. Let \( \tilde{w}_{\text{MMA}}^* \) and \( \tilde{w}_{\text{JMA}}^* \) be the bootstrap MMA and JMA weights by minimizing (3.1) and (3.3) based on the bootstrap sample \( \{z_1^*, \ldots, z_n^*\} \), respectively. The bootstrap MMA and JMA estimators are defined as \( \widehat{\beta}^* (\tilde{w}_{\text{MMA}}^*) = \sum_{m=1}^M \tilde{w}_{\text{MMA},m}^* \tilde{\beta}_m^* \) and \( \widehat{\beta}^* (\tilde{w}_{\text{JMA}}^*) = \sum_{m=1}^M \tilde{w}_{\text{JMA},m}^* \tilde{\beta}_m^* \) where \( \tilde{\beta}_m^* = \Pi_m'(X_m^s X_m')^{-1}X_m^s y^* \). Let \( \tilde{\beta}_j^*(\tilde{w}^*) \) be the \( j \)th component of \( \widehat{\beta}^*(\tilde{w}^*) \), where \( \tilde{w}^* \) is either \( \tilde{w}_{\text{MMA}}^* \) or \( \tilde{w}_{\text{JMA}}^* \). Let \( \tilde{q}_j^*(\alpha) \) be the \( \alpha \)th quantile of the bootstrap distribution of \( |\sqrt{n}(\tilde{\beta}_j^*(\tilde{w}^*) - \tilde{\beta}_j(\tilde{w}))| \). For MMA-B and JMA-B, the bootstrap confidence interval of \( \beta_j \) is constructed as

\[
\text{CI}_n = \left[ \tilde{\beta}_j(\tilde{w}) - n^{-1/2}\tilde{q}_j^*(\alpha), \tilde{\beta}_j(\tilde{w}) + n^{-1/2}\tilde{q}_j^*(\alpha) \right]. \tag{6.7}
\]

The modified JMA estimator is calculated based on (5.3). Let \( \tilde{\beta}_j(\tilde{w}_{\text{JMA}}) \) be the \( j \)th component of \( \tilde{\beta}(\tilde{w}_{\text{JMA}}) \). For JMA-M, the confidence interval of \( \beta_j \) is constructed as

\[
\text{CI}_n = \left[ \tilde{\beta}_j(\tilde{w}_{\text{JMA}}) - z_{1-\alpha/2}s(\tilde{\beta}_j(m)), \tilde{\beta}_j(\tilde{w}_{\text{JMA}}) + z_{1-\alpha/2}s(\tilde{\beta}_j(m)) \right], \tag{6.8}
\]

\(^8\)As an alternative, one could consider a residual bootstrap method to construct the confidence intervals for MMA and JMA. However, the simulation shows that the residual bootstrap method does not perform well as the pairs bootstrap method.
where \( m = M_0 + 1 \).

For each setting, we generate \( R = 499 \) and \( B = 499 \) random samples to construct the simulation-based confidence intervals and bootstrap confidence intervals, respectively. To evaluate the finite sample behavior of each estimator, we focus on the estimate of \( \beta_4 \). We report the variance (Var), the mean square error (MSE), the median absolute deviation (MAD), the coverage probability of a nominal 95% confidence interval (CP(95)), and the average length of the confidence intervals (Len). The number of Monte Carlo experiments is 500.

### 6.3 Simulation Results

Tables 1 and 2 present the finite sample performance of the least square averaging estimators and other approaches for \( n = 100 \) and \( n = 400 \), respectively. We first compare the variance, MSE, and MAD of the least square averaging estimators with alternative estimators. The simulation results show that JMA-M performs well and dominates other estimators in most cases. When the sample size is small, i.e., \( n = 100 \), MMA and JMA have similar variances and MSEs for the homoskedastic setup, but JMA has a smaller variance and MSE than MMA for the heteroskedastic setup. Both MMA and JMA achieve much lower variances and MSEs than other estimators, including JUST, FULL, AIC, and ALASSO, in both homoskedastic and heteroskedastic setups. When the sample size is large, i.e., \( n = 400 \), the variances and MSEs of MMA and JMA are similar, and both MMA and JMA have smaller variances and MSEs than other estimators except JMA-M. The MAD of most estimators are quite similar, except that JUST and FULL have larger MADs for \( n = 100 \).

We now compare the coverage probability and the average length of the confidence intervals of the least square averaging estimators with other estimators. As we expected, the coverage probabilities of JUST and FULL are close to the nominal values in most cases, but the coverage probabilities of the naive confidence intervals for AIC and BIC are much lower than the nominal values. Unlike the naive method, the coverage probabilities of MMA-S and JMA-S are close to the nominal values in most cases. Furthermore, the average length of the confidence intervals of MMA-S and JMA-S are much shorter than those of other estimators.

The simulation results also show that the coverage probabilities of ALASSO and JMA-M generally achieve the nominal values. The average length of the confidence intervals of JMA-M is the same as that based on JUST, which is shorter than that based on FULL. Both MMA-B and JMA-B perform well, and the average length of the confidence intervals
of MMA-B and JMA-B are shorter than those based on JUST and ALASSO. Comparing the results of Cases 1–3, we find that the performance of least square averaging estimators is relatively unaffected by the ordering of regressors.

We now consider an extended setup to investigate the effect of the number of models on the mean squared error and the coverage probability. The data generating process is based on (6.1) and the regression coefficients are determined by the following rule: \( \beta = (1, 1, c, c^2, \ldots, c^{k_0}, 0_{1 \times k_0})' \). The number of irrelevant variables \( k_0 \) is varied between 3, 5, and 7, and hence the numbers of models are 7, 11, and 15 for \( k_0 = 3, 5, \) and 7, respectively.

Tables 3 and 4 reports simulation results for \( M = 7, 11, \) and 15. The variances and MSEs of most estimators slightly increase as the number of models increases when \( n = 400 \), but they are quite similar for \( M = 7, 11, \) and 15 when \( n = 100 \). Similar to Tables 1 and 2, the coverage probabilities of MMA-S and JMA-S generally achieve the nominal values in most cases, and the average length of the confidence intervals are much shorter than those of other estimators in all cases. Overall, the finite sample performance of most estimators is quite robust to different values of \( k_0 \).

## 7 Conclusion

In this paper, we study the asymptotic behavior of two commonly used model averaging estimators, the MMA and JMA estimators, under the standard asymptotics with fixed parameters setup. We investigate the behavior of the MMA and JMA weights as \( n \to \infty \) and show that both MMA and JMA estimators have nonstandard asymptotic distributions. To address the inference after model averaging, we provide a simulation-based confidence interval for the least squares averaging estimator and propose a modified JMA estimator with asymptotic normality. Simulations show that the coverage probabilities of proposed confidence intervals generally achieve the nominal values. It would be greatly desirable to extend the method to non-nested candidate models.\(^9\)

\(^9\)It is not straightforward to extend our results to the non-nested models. This is because there is no simple relationship between the squared sum of residuals of the just-fitted or over-fitted model with the product of residual vectors of two non-nested under-fitted models.
Appendix

A Proofs

Proof of Theorem 1: Let \( l = (1, \ldots, 1)' \), an \( M \)-dimensional vector. Since \( \sum_{m=1}^{M} w_m = 1 \), we have \( w'K = w'K'l = w'K'w \). Thus, \( 2w'K = w'(K_m + K_j)_{m,j \in \{1, \ldots, M\}}w \). Let \( a_m = y'(I_n - P_m)y \) and \( \Phi \) be an \( M \times M \) matrix with the \( m \)-th element

\[
\Phi_{mj} = a_{\max\{m,j\}} + \hat{\sigma}^2 (K_m + K_j).
\] (A.1)

It is easily to verify that \( \mathcal{C}(w) = w'\Phi w \) for any \( w \in W \), and \( a_m \leq a_j \) for \( m > j \). Let \( m \) be an index belonging to \( \{1, \ldots, M_0\} \). Define

\[
\hat{w}_m = (\hat{w}_{\text{MMA},1}, \ldots, \hat{w}_{\text{MMA},m-1}, 0, \hat{w}_{\text{MMA},m+1}, \ldots, \hat{w}_{\text{MMA},M_0}, \ldots, \hat{w}_{\text{MMA},M} + \hat{w}_{\text{MMA},m})'.
\]

Then it follows that

\[
0 \leq \mathcal{C}(\hat{w}_m) - \mathcal{C}(\hat{w}_{\text{MMA}})
= \hat{w}_m'\Phi\hat{w}_m - \hat{w}_{\text{MMA}}'\Phi\hat{w}_{\text{MMA}}
= (\hat{w}_m + \hat{w}_{\text{MMA}})'\Phi(\hat{w}_m - \hat{w}_{\text{MMA}})
= (2\hat{w}_{\text{MMA}}' + (0, \ldots, 0, -\hat{w}_{\text{MMA},m}, 0, \ldots, 0, \hat{w}_{\text{MMA},m}))\Phi(0, \ldots, 0, -\hat{w}_{\text{MMA},m}, 0, \ldots, 0, \hat{w}_{\text{MMA},m})'
= \hat{w}_{\text{MMA},m}^2(a_m - a_M) + 2\hat{w}_{\text{MMA}}'\Phi(0, \ldots, 0, -\hat{w}_{\text{MMA},m}, 0, \ldots, 0, \hat{w}_{\text{MMA},m})'
= \hat{w}_{\text{MMA},m}^2(a_m - a_M) + 2\hat{w}_{\text{MMA},m}\hat{w}_{\text{MMA}}(\Phi_{1} - \Phi_{1m}, \ldots, \Phi_{M} - \Phi_{Mm})'
= \hat{w}_{\text{MMA},m}^2(a_m - a_M) + 2\hat{w}_{\text{MMA},m}\sum_{j=1}^{M} \hat{w}_{\text{MMA},j}(\Phi_{Mj} - \Phi_{mj})
= \hat{w}_{\text{MMA},m}^2(a_m - a_M) + 2\hat{w}_{\text{MMA},m}\sum_{j=1}^{M} \hat{w}_{\text{MMA},j}(a_m - a_{\max\{m,j\}} + \hat{\sigma}^2 K_M - \hat{\sigma}^2 K_m)
\leq \hat{w}_{\text{MMA},m}^2(a_m - a_M) + 2\hat{w}_{\text{MMA},m}^2(a_m - a_M) + 2\hat{w}_{\text{MMA},m}\hat{\sigma}^2 \sum_{j=1}^{M} \hat{w}_{\text{MMA},j}(K_M - K_m)
= \hat{w}_{\text{MMA},m}^2(a_m - a_M) + 2\hat{w}_{\text{MMA},m}(a_m - a_M) + 2\hat{w}_{\text{MMA},m}\hat{\sigma}^2 (K_M - K_m). \tag{A.2}
\]

Thus, when \( \hat{w}_{\text{MMA},m} \neq 0 \), we have

\[
\hat{w}_{\text{MMA},m} \leq (a_m - a_M)^{-1}2\hat{\sigma}^2 (K_M - K_m). \tag{A.3}
\]

Let \( \beta_m = \Pi_{mv}\beta \). It is straightforward to show that for any \( m \in \{1, \ldots, M_0\} \),

\[
a_m - a_M
\]

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\[
\begin{align*}
&= (e + X_m \beta_m)'(I_n - P_{m_e})(e + X_m \beta_m) - e'(I_n - P_M)e \\
&= (X_m \beta_m)'(I_n - P_s)(X_m \beta_m) + 2e'(I_n - P_m)X_m \beta_m - e'(P_s - P_M)e. \quad \text{(A.4)}
\end{align*}
\]

From Conditions (C.1)-(C.2), for any \( j \in \{1, \ldots, M\} \), we obtain that
\[
e'P_je = O_p(1), \quad e'(I_n - P_j)X_j \beta_j = O_p(1) \quad \text{(A.5)}
\]
and
\[
\hat{\sigma}^2 = O_p(1). \quad \text{(A.6)}
\]

It follows from Condition (C.1) that there exists a positive definite matrix \( \tilde{Q} \) such that
\[
n^{-1}[X_m, X_{m_c}'][X_m, X_{m_c}] = n^{-1} \begin{bmatrix} X_m'X_m & X_m'X_{m_c} \\ X_m'X_m & X_m'X_{m_c} \end{bmatrix} \rightarrow \tilde{Q} = \begin{bmatrix} \tilde{Q}_{11} & \tilde{Q}_{12} \\ \tilde{Q}_{21} & \tilde{Q}_{22} \end{bmatrix}.
\]
In addition, \( X \) is assumed to be of full column rank, and it is well known that
\[
\begin{vmatrix} \tilde{Q}_{11} & \tilde{Q}_{12} \\ \tilde{Q}_{21} & \tilde{Q}_{22} \end{vmatrix} = |\tilde{Q}_{11}| |\tilde{Q}_{22} - \tilde{Q}_{21}\tilde{Q}_{11}\tilde{Q}_{12}|,
\]
so \( |\tilde{Q}_{22} - \tilde{Q}_{21}\tilde{Q}_{11}\tilde{Q}_{12}| > 0 \), which, along with Condition (C.1), implies
\[
n^{-1}(X_{m_c} \beta_{m_c})'(I_n - P_s)(X_{m_c} \beta_{m_c}) \\
= n^{-1}\beta_{m_c}'\{X_m'X_{m_c} - X_m'X_m(X_m'X_m)^{-1}X_m'X_{m_c}\}\beta_{m_c} \\
\rightarrow \beta_{m_c}'(\tilde{Q}_{22} - \tilde{Q}_{21}\tilde{Q}_{11}\tilde{Q}_{12})\beta_{m_c} > 0. \quad \text{(A.7)}
\]

From (A.4), (A.5) and (A.7), we have
\[
n(a_m - a_M)^{-1} = O_p(1). \quad \text{(A.8)}
\]

The result (4.1) is implied by (A.3), (A.6) and (A.8).

**Proof of Theorem 2:** Let \( \Phi^* = \Phi - \|e\|^2l' \), where the second term \( \|e\|^2l' \) is unrelated to \( w \). Therefore, we have
\[
\hat{w}_{\text{MMA}} = \arg\min_{w \in \mathcal{W}} w'\Phi^*w.
\]
Rewrite \( \hat{w}_{\text{MMA}} = (\hat{w}_1', \hat{w}_2')' \) such that \( \hat{w}_1 \) contains weights of under-fitted models. Correspondingly, we also rewrite \( \Phi^* \) as
\[
\Phi^* = \begin{pmatrix} \Phi^*_{11} & \Phi^*_{12} \\ \Phi^*_{21} & \Phi^*_{22} \end{pmatrix}.
\]

From Conditions (C.1)-(C.2), we have \( n^{-1}(a_m - \|e\|^2) = O_p(1) \) for \( 1 \leq m \leq M_0 \) and
\[
a_m - \|e\|^2 = O_p(1)
\]

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for $M_0 < m \leq M$. Thus, by (4.1) we have

$$\hat{\tau}_1 \equiv \hat{\mathbf{w}}_1^* \mathbf{\Phi}_{11}\mathbf{w}_1 = o_p(1) \quad \text{and} \quad \hat{\tau}_2 \equiv \hat{\mathbf{w}}_1^* \mathbf{\Phi}_{12}\mathbf{w}_2 = o_p(1),$$

(A.9)

where $\hat{\tau}_1$ and $\hat{\tau}_2$ are two scales. Let $S = M - M_0$ so that $\mathbf{\Phi}_{22}^*$ is an $S \times S$ matrix. From (A.1), we know that the $(s, j)$th element of $\mathbf{\Phi}_{22}^*$ can be written as

$$\mathbf{\Phi}_{22,sj}^* = \tau_0^2(K_{M_0+s} - K_{M_0+j}) - \mathbf{e}' \mathbf{P}_{M_0+\max\{s,j\}} \mathbf{e},$$

which converges to $\Gamma_{sj}$ (defined in (4.4)) in distribution. As in the proof of Theorem 3 of Liu (2015), by Theorem 3.2.2 of Van der Vaart and Wellner (1996) or Theorem 2.7 of Kim and Pollard (1990), we have $\hat{\mathbf{w}}_2 \to \hat{\lambda}_{\mathbf{MMA}}$ in distribution. From Conditions (C.1)-(C.2), we know that for any $m \in \{1, \ldots, M_0\}$,

$$\hat{\beta}_m = \Pi_m'(\mathbf{X}_m^\prime \mathbf{X}_m)^{-1}\mathbf{X}_m^\prime \mathbf{y} = \Pi_m'(\mathbf{X}_m^\prime \mathbf{X}_m)^{-1}\mathbf{X}_m^\prime \beta + \Pi_m'(\mathbf{X}_m^\prime \mathbf{X}_m)^{-1}\mathbf{X}_m^\prime \mathbf{e} = O_p(1).$$

(A.10)

Thus, from (4.1), we have

$$\sqrt{n} \left( \hat{\beta}_m^{\mathbf{MMA}} - \beta \right) = \sum_{m=1}^{M_0} \hat{\mathbf{w}}_{\mathbf{MMA},m} \sqrt{n} \left( \hat{\beta}_m - \beta \right) + \sum_{m=M_0+1}^{M} \hat{\mathbf{w}}_{\mathbf{MMA},m} \sqrt{n} \left( \hat{\beta}_m - \beta \right) = \sum_{m=1}^{M_0} \hat{\mathbf{w}}_{\mathbf{MMA},m} \sqrt{n} \Pi_m'(\mathbf{X}_m^\prime \mathbf{X}_m)^{-1}\mathbf{X}_m^\prime \mathbf{e} = O_p(n^{-1/2}) + \sum_{m=M_0+1}^{M} \hat{\mathbf{w}}_{\mathbf{MMA},m} \Pi_m'(\mathbf{I}_m \mathbf{Q}_m \Pi_m')^{-1} \mathbf{I}_m \mathbf{Z}_m.$$  

(A.11)

In addition, both $\hat{\lambda}_{\mathbf{MMA},s}$ and $\mathbf{V}_s$ can be expressed in terms of $\mathbf{Z}$ and $\mathbf{Q}$. Thus, the result (4.3) holds.

Proof of Theorem 3: Denote $\mathbf{C}_m$ as an $n \times n$ diagonal matrix with the $i$th diagonal element

$$C_{m,ii} = h_{ii}^m/(1 - h_{ii}^m).$$

Therefore, we have $\mathbf{D}_m = \mathbf{C}_m + \mathbf{I}_n$. Let $\mathbf{\Psi}$ be an $M \times M$ matrix with the $(m, j)$th element

$$\Psi_{mj} = (\mathbf{e} + \mathbf{X}_m \beta_m)^\prime (\mathbf{I}_n - \mathbf{P}_m)(\mathbf{C}_m + \mathbf{C}_j + \mathbf{C}_m \mathbf{C}_j)(\mathbf{I}_n - \mathbf{P}_j)(\mathbf{e} + \mathbf{X}_j \beta_j) - 2K_m \hat{\sigma}^2.$$

Therefore, it follows that

$$\mathbf{y}'(\mathbf{I}_n - \mathbf{P}_m)\mathbf{D}_m \mathbf{D}_j (\mathbf{I}_n - \mathbf{P}_j) \mathbf{y} = \mathbf{y}'(\mathbf{I}_n - \mathbf{P}_m)(\mathbf{I}_n + \mathbf{C}_m + \mathbf{C}_j + \mathbf{C}_m \mathbf{C}_j)(\mathbf{I}_n - \mathbf{P}_j) \mathbf{y}.$$
\[ J(w) = C(w) + w' \Psi w. \]  

(A.12)

Let \( m \) be an index belonging to \( \{1, \ldots, M_0\} \). Define

\[ \mathbf{w}_m = (\hat{w}_{JMA,1}, \ldots, \hat{w}_{JMA,m-1}, 0, \hat{w}_{JMA,m+1}, \ldots, \hat{w}_{JMA,M}, \hat{w}_{JMA,M} + \hat{w}_{JMA,m})'. \]

Using (A.12), we have

\[
0 \leq J(\mathbf{w}_m) - J(\hat{\mathbf{w}}_{JMA}) = C(\mathbf{w}_m) - C(\hat{\mathbf{w}}_{JMA}) + \mathbf{w}_m' \Psi \mathbf{w}_m - \hat{\mathbf{w}}_{JMA}' \Psi \hat{\mathbf{w}}_{JMA} \\
= C(\mathbf{w}_m) - C(\hat{\mathbf{w}}_{JMA}) + \hat{\mathbf{w}}_{JMA,m}'(\Psi_{MM} + \Psi_{mm} - \Psi_{Mm} - \Psi_{mm}) \\
+ 2\hat{w}_{JMA,m} \sum_{j=1}^{M} \hat{w}_{JMA,j}(\Psi_{Mj} - \Psi_{mj}).
\]

So similar to (A.3), we know that when \( \hat{w}_{JMA,m} \neq 0, \)

\[
\hat{w}_{JMA,m} \leq (a_m - a_M)^{-1} \left( 2\hat{\sigma}^2(K_M - K_m) + \hat{w}_{JMA,m}(\Psi_{MM} + \Psi_{mm} - \Psi_{Mm} - \Psi_{mm}) \\
+ 2 \sum_{j=1}^{M} \hat{w}_{JMA,j}(\Psi_{Mj} - \Psi_{mj}) \right). \]

(A.13)

Let \( \mathcal{S}(A) \) be the largest singular value of a matrix \( A \). We know that any two \( n \times n \) matrices \( A \) and \( B \),

\[
\mathcal{S}(AB) \leq \mathcal{S}(A)\mathcal{S}(B) \quad \text{and} \quad \mathcal{S}(A + B) \leq \mathcal{S}(A) + \mathcal{S}(B),
\]

which, along with Conditions (C.1)-(C.3), implies that for any \( m, j \in \{1, \ldots, M\}, \)

\[
(e + X_{mC} \beta_{mC})'(I_n - P_m)(C_m + C_j + C_mC_j)(I_n - P_j)(e + X_{jC} \beta_{jC}) \\
\leq \|e + X_{mC} \beta_{mC}\|\|e + X_{jC} \beta_{jC}\|S\{(I_n - P_m)(C_m + C_j + C_mC_j)(I_n - P_j)\} \\
\leq \|e + X_{mC} \beta_{mC}\|\|e + X_{jC} \beta_{jC}\|\{2\hat{h}_n + (\bar{h}_n)^2\} \\
= o_p(n^{1/2}), \quad \text{ (A.14)}
\]

From (A.6), (A.12) and (A.14), we know that \( \Psi_{mj} = o_p(n^{1/2}) \) for any \( m, j \in \{1, \ldots, M\}, \)

which, along with (A.6), (A.8) and (A.13), implies (4.5).
Proof of Theorem 4: From (A.12), we need to focus on $\Psi$. It is seen that for any $m \in \{1, \ldots, M\}$,

$$
e'diag(P^m_{11}, \ldots, P^m_{nn})e = \sum_{i=1}^{n} e'^2x'_{m,i}(X_m X_m)^{-1}x_{m,i}$$

$$= \text{tr}\left((n^{-1}X_m X_m)^{-1}n^{-1}\sum_{i=1}^{n} e'^2x_{m,i}x'_{m,i}\right)$$

$$= \text{tr}\left((\Pi_m Q_n \Pi'_m)^{-1}\Pi_m \Omega_n \Pi'_m\right).$$

From Condition (C.3), similar to (A.14), we have that for any $m \in \{1, \ldots, M\}$,

$$e'P_m(C_m + C_j + C_m C_j)(I_n - P_j)e \leq \|P_m e\|S((C_m + C_j + C_m C_j)(I_n - P_j))\|e\|$$

$$\leq \|P_m e\|\|e\|$$

$$= o_p(1).$$

Similarly,

$$e'P_m(C_m + C_j + C_m C_j)P_j e = o_p(1).$$

From the above results, we have, for $m, j \notin \{1, \ldots, M_0\}$,

$$\Psi_{mj} = e'(I_n - P_m)(C_m + C_j + C_m C_j)(I_n - P_j)e - 2K_m\sigma^2$$

$$= \text{tr}\left((\Pi_m Q_n \Pi'_m)^{-1}\Pi_m \Omega_n \Pi'_m\right) + \text{tr}\left(\Pi_j Q_n \Pi'_j\right)^{-1}\Pi_j \Omega_n \Pi'_j\right) + \hat{r}_{mj} - 2K_m\hat{\sigma}^2,$$

where $\hat{r}_{mj} = o_p(1)$. Now, by Condition (C.4) and arguments similar to the proof of (4.3), we can obtain (4.6).

Proof of Theorem 5: Let $m$ be an index belonging to $\{M_0 + 2, \ldots, M\}$.

Define

$$\tilde{w}_m = (\tilde{w}_{\text{JMA},1}, \ldots, \tilde{w}_{\text{JMA},M_0+1} + \tilde{w}_{\text{JMA},m}, \tilde{w}_{\text{JMA},M_0+2}, \ldots, \tilde{w}_{\text{JMA},m-1}, 0, \tilde{w}_{\text{JMA},m+1}, \ldots, \tilde{w}_{\text{JMA},M})'.$$

Using the derivation steps in (A.2), we have $\tilde{w}'_m \Phi \tilde{w}_m - \tilde{w}'_{\text{JMA}} \Phi \tilde{w}_{\text{JMA}} = O_p(1)$. Then, from (A.5), (A.6), (A.12) and (A.14), we know that

$$\tilde{J}(\tilde{w}_m) - \tilde{J}(\tilde{w}_{\text{JMA}})$$

$$= \tilde{w}'_m \Phi \tilde{w}_m - \tilde{w}'_{\text{JMA}} \Phi \tilde{w}_{\text{JMA}} + (\phi_n - 2\hat{\sigma}^2)\tilde{w}_{\text{JMA},m}(K_{M_0+1} - K_m) + O_p(1)$$

$$= O_p(1) + (\phi_n - 2\hat{\sigma}^2)\tilde{w}_{\text{JMA},m}(K_{M_0+1} - K_m) + O_p(1).$$

(A.15)

Since $\tilde{w}_{\text{JMA}} = \arg\min_{w \in W} \tilde{J}(w)$, we have $\tilde{J}(\tilde{w}_{\text{JMA}}) \leq \tilde{J}(\tilde{w}_m)$, which along with (A.15) and $K_{M_0+1} - K_m < 0$ implies that

$$(\phi_n - 2\hat{\sigma}^2)\tilde{w}_{\text{JMA},m}(K_m - K_{M_0+1}) = O_p(1).$$

(A.16)
The above result together with (A.6) and \( \phi_n \to \infty \) implies that \( \bar{w}_{JMA,m} = O_p(\phi_n^{-1}) \), which is (5.4).

From the proofs of Theorem 1 and Theorem 3 and Conditions (C.1)-(C.3), it is straightforward to obtain that for any \( m \in \{1, \ldots, M_0\} \), we have

\[
\bar{w}_{JMA,m} = O_p(\phi_n/n) + o_p(n^{-1/2}).
\] (A.17)

Now, by (5.4), (A.10), (A.17), Conditions (C.1)-(C.2) and (C.4), and \( \phi_n n^{-1/2} \to 0 \), we have (5.5).
## B Tables

Table 1: Simulation results in three cases for $n = 100$

<table>
<thead>
<tr>
<th>Case</th>
<th>Method</th>
<th>Variance</th>
<th>MSE</th>
<th>MAD</th>
<th>CP(95)</th>
<th>Length</th>
<th>Variance</th>
<th>MSE</th>
<th>MAD</th>
<th>CP(95)</th>
<th>Length</th>
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<td>0.244</td>
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<td>0.950</td>
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<td>0.343</td>
<td>0.415</td>
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<td>0.289</td>
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<td>0.379</td>
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Table 2: Simulation results in three cases for $n = 400$

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### Table 4: Simulation results for different number of models for $n = 400$

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